



AULA 02

INTRODUÇÃO AOS MÉTODOS

ESPECTRAIS

PTC 5725 (25/09/2025)



Interpolação baricêntrica

Interpolação de Lagrange
Função polyfit no Matlab

$$w_j = \prod_{m \neq j} (x_j - x_m)^{-1}$$

$$\ell_j(x) = \frac{\prod_{k \neq j} (x - x_k)}{\prod_{k \neq j} (x_j - x_k)} \quad L(x) = \sum_{j=0}^n \ell_j(x) \cdot f_j$$

Instabilidade

Se $x_j \approx x_k$, o erro relativo de $(x_j - x_k)^{-1}$
é expressivo!

$$L(x) = \frac{\sum_{j=0}^k \frac{w_j}{x - x_j} y_j}{\sum_{j=0}^k \frac{w_j}{x - x_j}}.$$



```
% The function p = polint(xk, fk, xnew) computes the polynomial interpolant
% of the data (xk, fk). Two or more data points are assumed.
%
% Input (constant weight)
% xk: Vector of x-coordinates of data (assumed distinct).
% fk: Vector of y-coordinates of data.
% xnew: Vector of x-values where polynomial interpolant is to be evaluated.
%
% Output:
% fkk: Vector of interpolated values.
% Mi: Matrix of interpolation
```

```
function [fnew,Mi] = Bary_Generic(xk, fk, xnew)
```

```
    xnew = xnew(:); % Make sure the data are column vectors
    xk = xk(:); fk = fk(:);
```

```
    N = length(xk);
    L = logical(eye(N));
```

```
    D = xk(:,ones(1,N))-xk(:,ones(1,N))'; % Compute the weights w(k)
    D(L) = ones(N,1);
    w = 1./prod(D)';
```

```
%%
Mi = bsxfun(@minus,xnew,xk'); %All xnew(j) - x(k)
Mi = bsxfun(@rdivide,w',Mi); %All w(k)/(xnew(j) - x(k))
Mi = bsxfun(@rdivide, Mi, sum(Mi,2)); % Normalization
Mi(isnan(Mi)) = 1; % Remove NaNs
%%
```

```
    fnew = Mi*fk;
```

```
end
```



$$f(x) = 10^3 \sin(\pi x) \quad x \in [-1, 1]$$

- Aproxime f por um polinômio de grau 21 (pontos de Cheby).
- Use interpolação de Lagrange p/ calcular f em 501 pontos equiespaçados.
- Compare com a interpolação baricêntrica.
- Compare com o resultado analítico.

Cheby Poly (I) T_n



$$x \in [-1, 1]$$

$$\theta \in [0, \pi]$$

$$T_n(\cos \theta) = \cos(n\theta)$$

$$x = \cos \theta$$

$$T_0(x) = 1 \text{ e } T_1(x) = x$$

$$\frac{dx}{d\theta} = -\sin \theta$$

Ortogonalidade $T_n(\cos \theta) = \cos(n\theta) = P_n(\theta)$

$$\int_0^\pi P_n \cdot P_m d\theta = \int_{-1}^1 T_n \cdot T_m \cdot \frac{1}{-\sin \theta} dx = \int_{-1}^1 T_n \cdot T_m \cdot \frac{1}{\sqrt{1-x^2}} dx$$

Portanto,

$$\langle T_n | T_m \rangle_w = \begin{cases} \pi / 2, & \text{se } m = n \neq 0 \\ \pi & \text{se } m = n = 0 \\ 0 & \text{se } m \neq n \end{cases}$$

$$\cos a \cdot \cos b = [\cos(a-b) + \cos(a+b)] / 2$$

$$\cos(m\theta) \cdot \cos(n\theta) = [\cos((m-n)\theta) + \cos((m+n)\theta)] / 2$$

$$\text{Se } m = n = 0 \Rightarrow \int_0^\pi 1 \cdot d\theta = \pi.$$

$$\text{Se } m = n \neq 0 \Rightarrow \int_0^\pi 1 \cdot d\theta / 2 + \underbrace{\int_0^\pi \cos(k\theta) \cdot d\theta / 2}_0 = \pi / 2 \quad k \in \mathbb{N}^*$$

$$\text{Se } m \neq n \Rightarrow \underbrace{\int_0^\pi \cos(k_1\theta) \cdot d\theta / 2}_0 + \underbrace{\int_0^\pi \cos(k_2\theta) \cdot d\theta / 2}_0 = 0$$

Cheby Series



$$f(x) \approx \sum' a_k T_k \quad a_k = \frac{2}{\pi} \int_{-1}^1 f \cdot T_k \frac{dx}{\sqrt{1-x^2}} = \frac{\langle f | T_k \rangle}{\langle T_k | T_k \rangle}$$

$$\text{Operador projetor: } \text{proj} = \frac{|T_k\rangle}{\langle T_k | T_k \rangle}$$



Lobatto points: $\theta_i = i \cdot \pi/n$, $i = n:-1:0$

$$x_i = \cos \theta_i$$

Matriz de Base ordem n

$$B_{i+1,j+1} = \cos(j\theta_i) = T_j(x_i)$$

$$B = \begin{bmatrix} T_0(x_0) & T_1(x_0) & \dots & T_n(x_0) \\ T_0(x_1) & & & \\ \vdots & & \ddots & \\ T_0(x_n) & & & T_n(x_n) \end{bmatrix}$$

"Inversa" da Base n

$$BI = \frac{1}{n} \begin{bmatrix} T_0(x_0)/2 & T_0(x_1) & \dots & T_0(x_n)/2 \\ 2T_1(x_0) & & & 2T_1(x_n) \\ \vdots & & \ddots & \\ T_n(x_0)/2 & T_n(x_1) & \dots & T_n(x_n)/2 \end{bmatrix}$$

Transformação Discreta (Exata p/ polinômios até grau n)

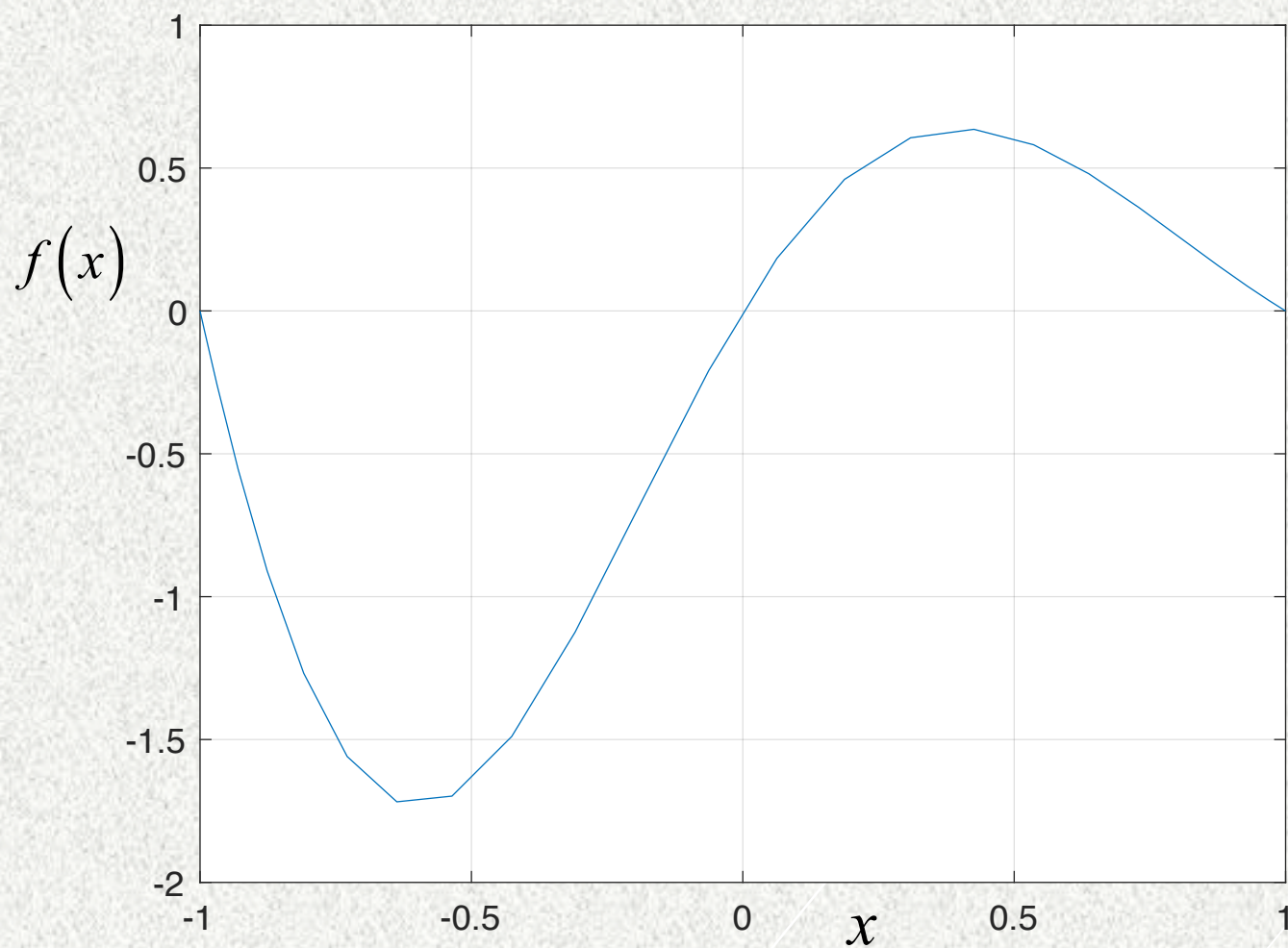
$$c_k = \frac{\alpha_k}{n} \sum_j T_k(x_j) p(x_j),$$

$\alpha_k = 1$ p/ $k = 0$ ou $k = n$ e $\alpha_k = 2$ p/ o resto.

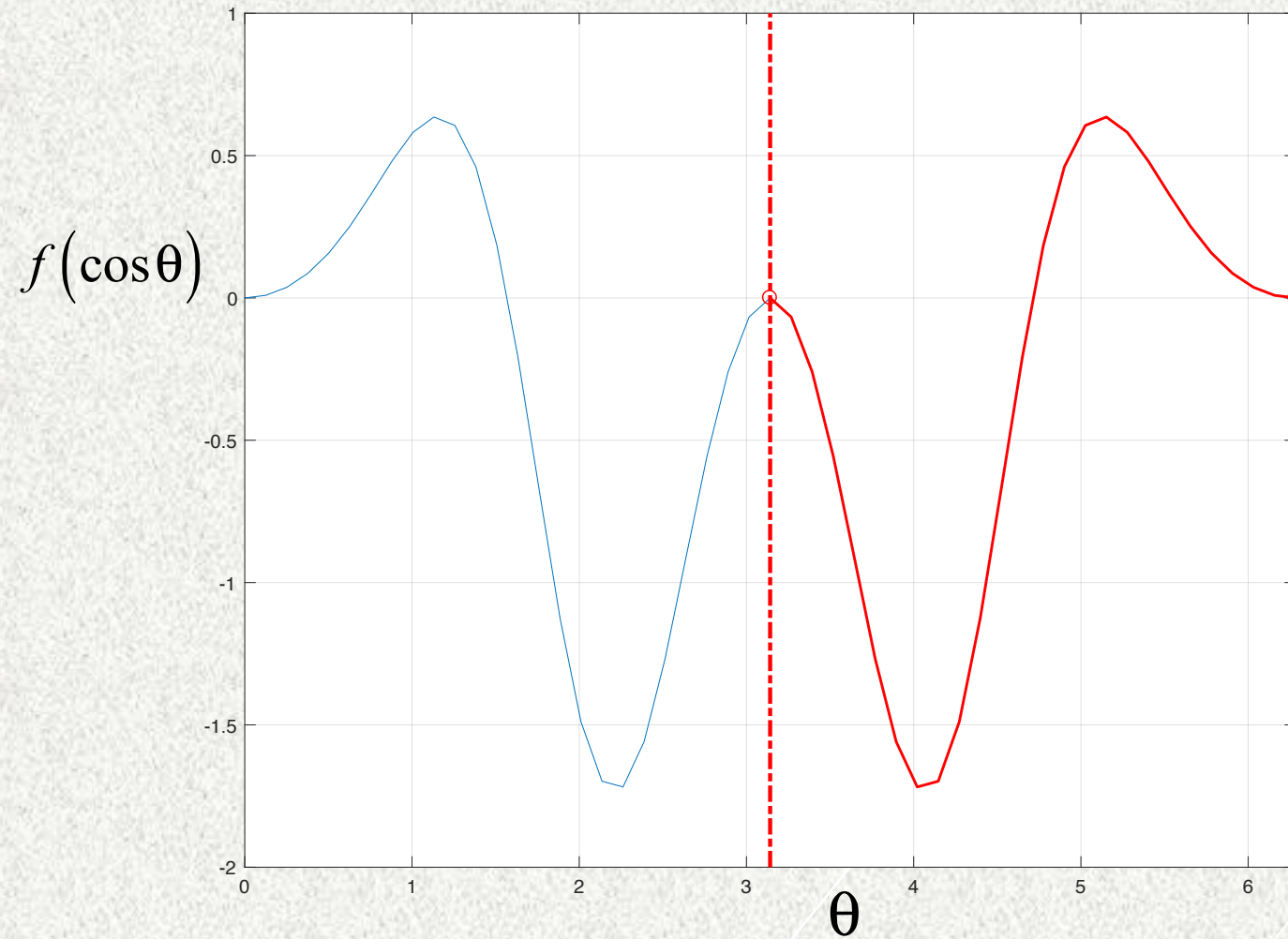
Supondo $f(x)$ polinomial de grau $\alpha \leq n$

$$f(x) = \langle B | \mathbf{A} \rangle_n \quad A = B^{-1} \cdot \mathbf{y}$$

$$f(x) = e^{-x} \sin(\pi x) \quad n = 25$$



Fast Fourier Transform



$$\cos(\pi - \theta) = \cos(\pi + \theta)$$



```
function B = FOU_CHB(A,direction)
% A - original data in columns
% B - transformed data in columns
% direction - set equal to 1 for nodal to spectral
%              anything else for spectral to physical

[N,M]=size(A);

if direction==1 % physical-to-spectral

    A = flipud(A);% TO FOLLOW THETA DIRECTION

    F=ifft([A(1:N,:);A(N-1:-1:2,:)]);

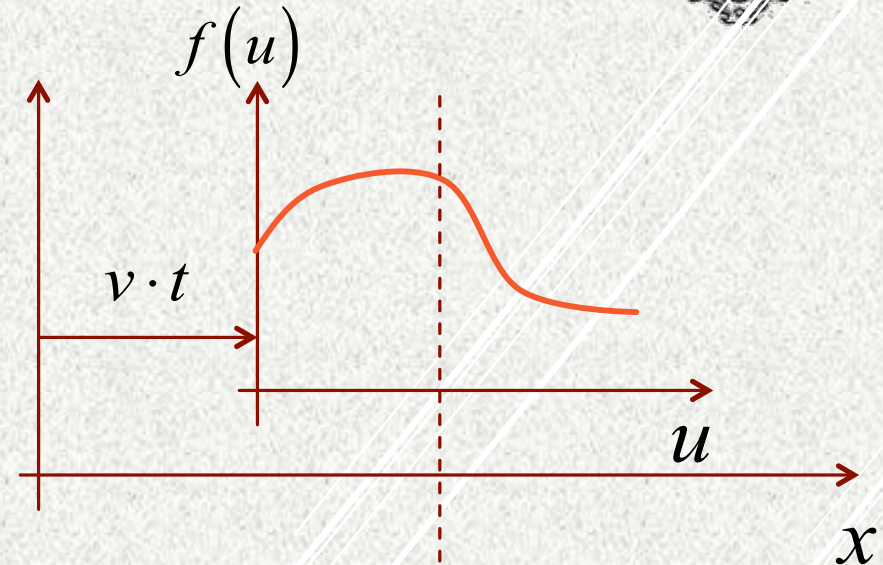
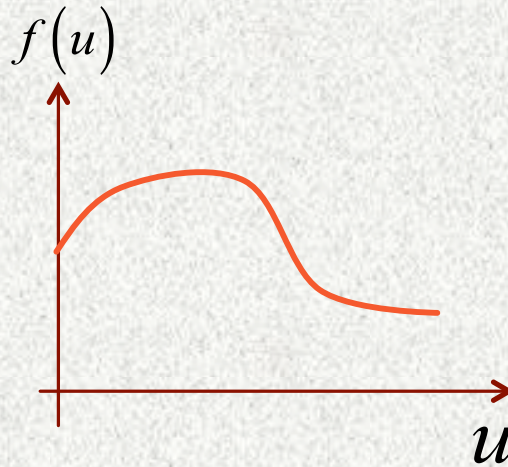
    B=( [F(1,:); 2*F(2:(N-1),:); F(N,:)]);

else % Spectral-to-physical

    F=fft([A(1,:); [A(2:N-1,:);2*A(N,:);A(N-1:-1:2,)]/2]);
    B = F(N:-1:1,:);

end
```

Equação da onda



Para cada abscissa u , temos: $f(u) = f(x - vt)$

$$x = u + v \cdot t \Rightarrow u = x - vt$$

$$\frac{\partial u}{\partial x} = 1 \quad \text{e} \quad \frac{\partial u}{\partial t} = -v$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial x} = \frac{\partial f}{\partial u}$$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial t} = \frac{\partial f}{\partial u}(-v)$$

Portanto:

$$\frac{\partial f}{\partial t} = -v \cdot \frac{\partial f}{\partial x}$$

$$\frac{\partial f}{\partial t} = -v \cdot \frac{\partial f}{\partial x}$$

Onda regressiva: $f = f(x + v \cdot t)$ 11

Em ambos os casos, f é arbitrária.



Série de Fourier

$$f(x) = \sum_{n=-\infty}^{\infty} A_n e^{inx}$$

$$A_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-inx} dx.$$



Para cada abscissa u , temos: $f(u) = f(x - vt)$

$$x = u + v \cdot t \Rightarrow u = x - vt$$

$$\frac{\partial u}{\partial x} = 1 \quad \text{e} \quad \frac{\partial u}{\partial t} = -v$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial^2 u}$$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial t} = \frac{\partial f}{\partial u}(-v) \quad \text{e} \quad \frac{\partial^2 f}{\partial t^2} = \frac{\partial^2 f}{\partial^2 u} \cdot v^2$$

$$\text{Portanto: } \frac{\partial^2 f}{\partial^2 u} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2} = \frac{\partial^2 f}{\partial x^2}$$

Equação da onda

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$$



Collocation



$$S \cdot \vec{y} = \vec{r}$$



Boundary Value Problems (BVP)

Programa 13

$$y_{xx} = e^{4x}, \quad y(\pm 1) = 0$$

Analiticamente: $y = \left[e^{4x} - x \cdot \sinh(4) - \cosh(4) \right] / 16.$

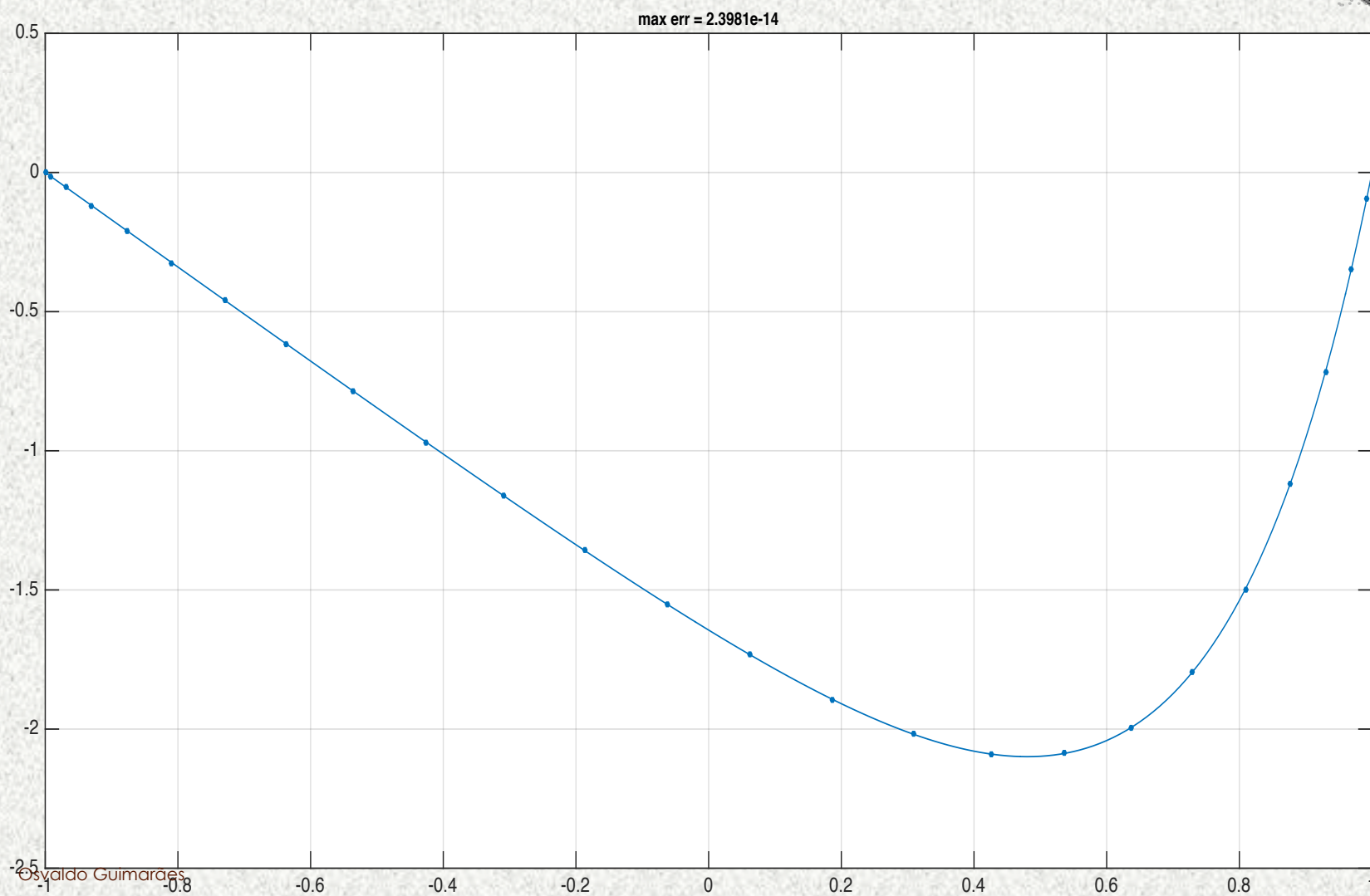
Equação matricial

$$D \cdot (D \cdot y) = f(x),$$

$$D^2 \cdot y = f,$$

- Linha 1 de $D: [1 \ 0 \ \dots \ 0]$ e $f_1 = y(-1) = 0$
- Linha $(n+1)$ de $D: [0 \ \dots \ 1]$ e $f_{n+1} = y(+1) = 0$

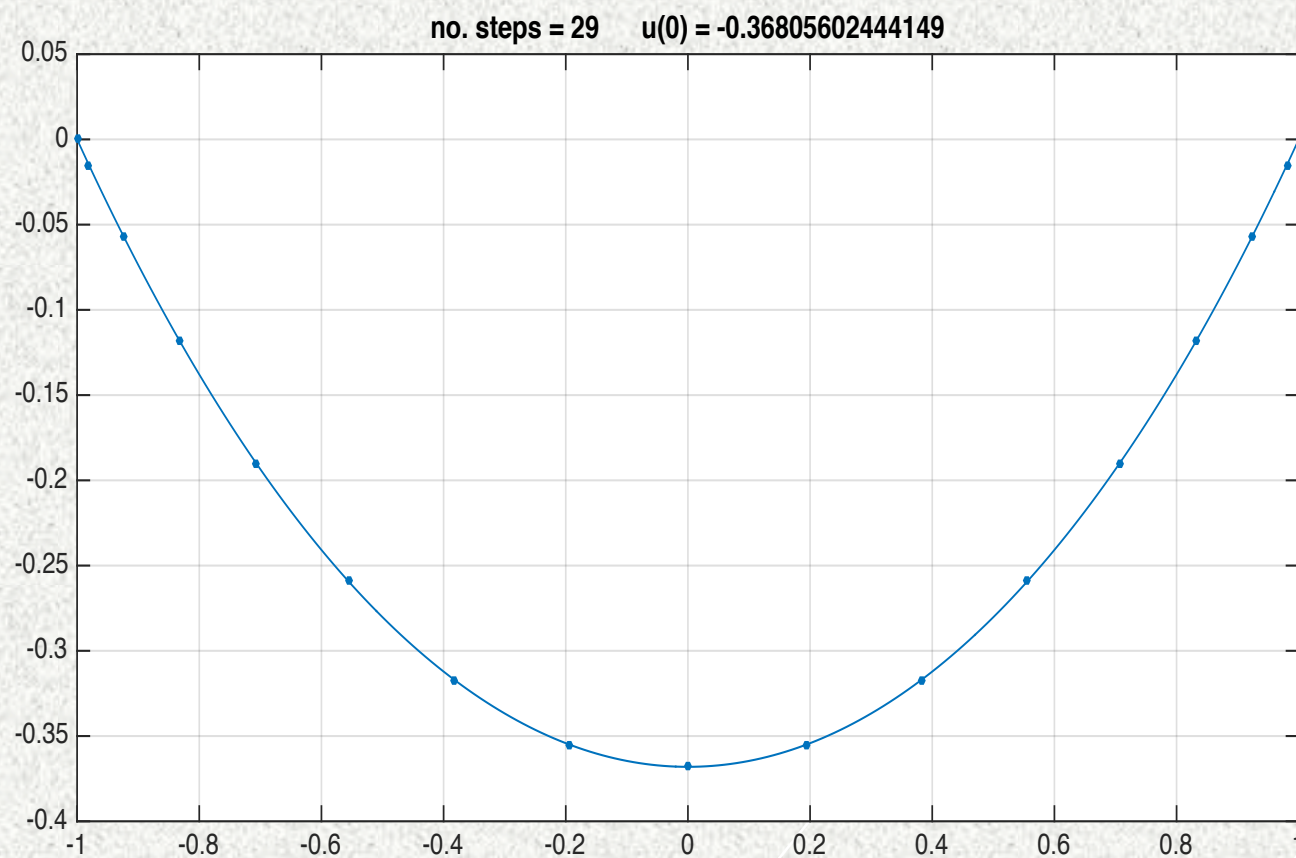
```
%% BVP p.13 - Alternative code  
N = 25;  
x = -cos( (0:N)*pi/N ).'; D = Generalized_Diff_Mat(x); D2 = D^2;  
D2([1,N+1],:) = 0; D2(1,1) = 1; D2(N+1,N+1) = 1;  
f = exp(4*x(2:N)); f = [0;f;0];  
u = D2\f;
```



Problema 14 - BVP não linear

$$y_{xx} = e^y, \quad y(\pm 1) = 0.$$

error \cong eps



Programa 15 - Autovalores



$$y_{xx} = -k^2 y, \quad y(\pm 1) = 0.$$

Equação matricial

$$D^2 \cdot y = -k^2 y,$$

$$y(\pm 1) = 0$$

Soluções estacionárias c/ período máximo 4 ($2L$).

$$\omega_1 = \frac{2\pi}{4} = \pi/2 \text{ rad/s} \quad \omega_n = n \cdot \omega_1.$$

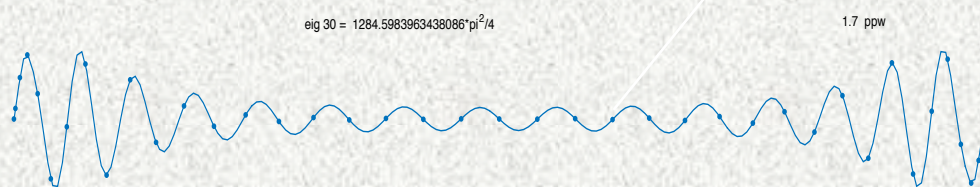
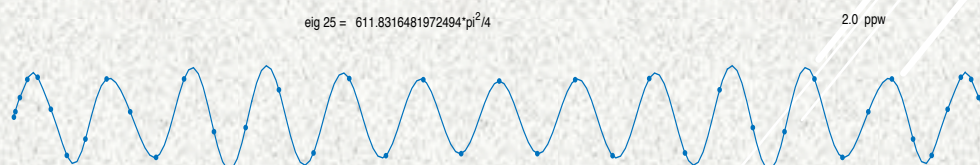
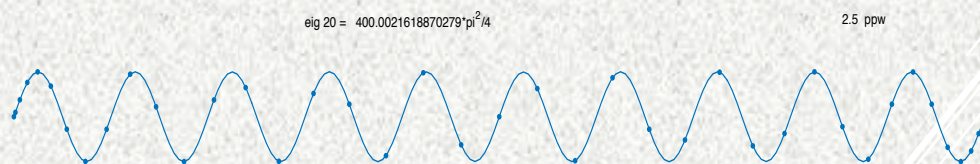
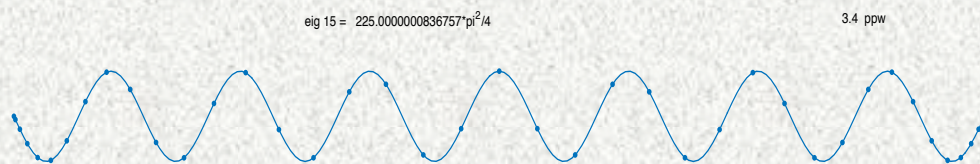
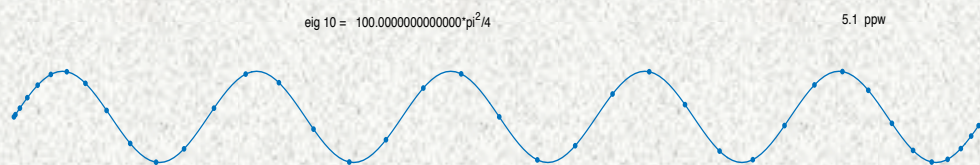
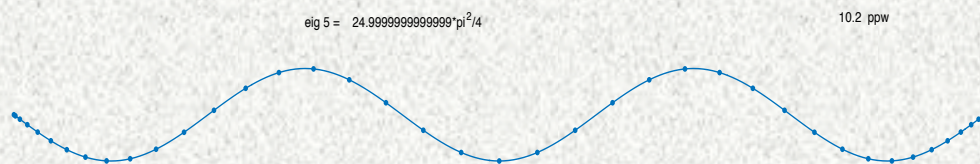


%% Alternative code

```
N = 40;  
x = -cos( (0:N)*pi/N ).'; D = Generalized_Diff_Mat(x); D2 = D^2;  
D2([1,N+1],:) = 0; D2(:,[1,N+1])=0 ;  
[V,lam] = eig(D2,'vector');  
[lam,ii] = sort(-lam(lam<0)); % sort eigenvalues and -vectors  
V = V(:,ii);
```

Autovalores

$$k_n^2 = \left(n \frac{2\pi}{T} \right)^2 = n^2 \frac{\pi^2}{4}$$





TAREFA

I) Código para montar as matrizes do slide 7, dado n , com

$$x = -\cos(k\pi/n), \quad k = 0:n$$

II) Código para obter os coeficientes de Cheby usando FFT, a partir dos valores da função nos nodos, conforme slide 10.

III) Resolver numericamente:

Série de Chebyshev (grau 7 ou 8):

$$\frac{x^2}{20} y'' + x \cdot y' - y - 5x^5 + 1 = 0, \quad \text{com } x \in [-1, 1] \quad y(-1) = 2 \text{ e } y(1) = 0$$

Testar todas as resoluções e enviar em pdf.