

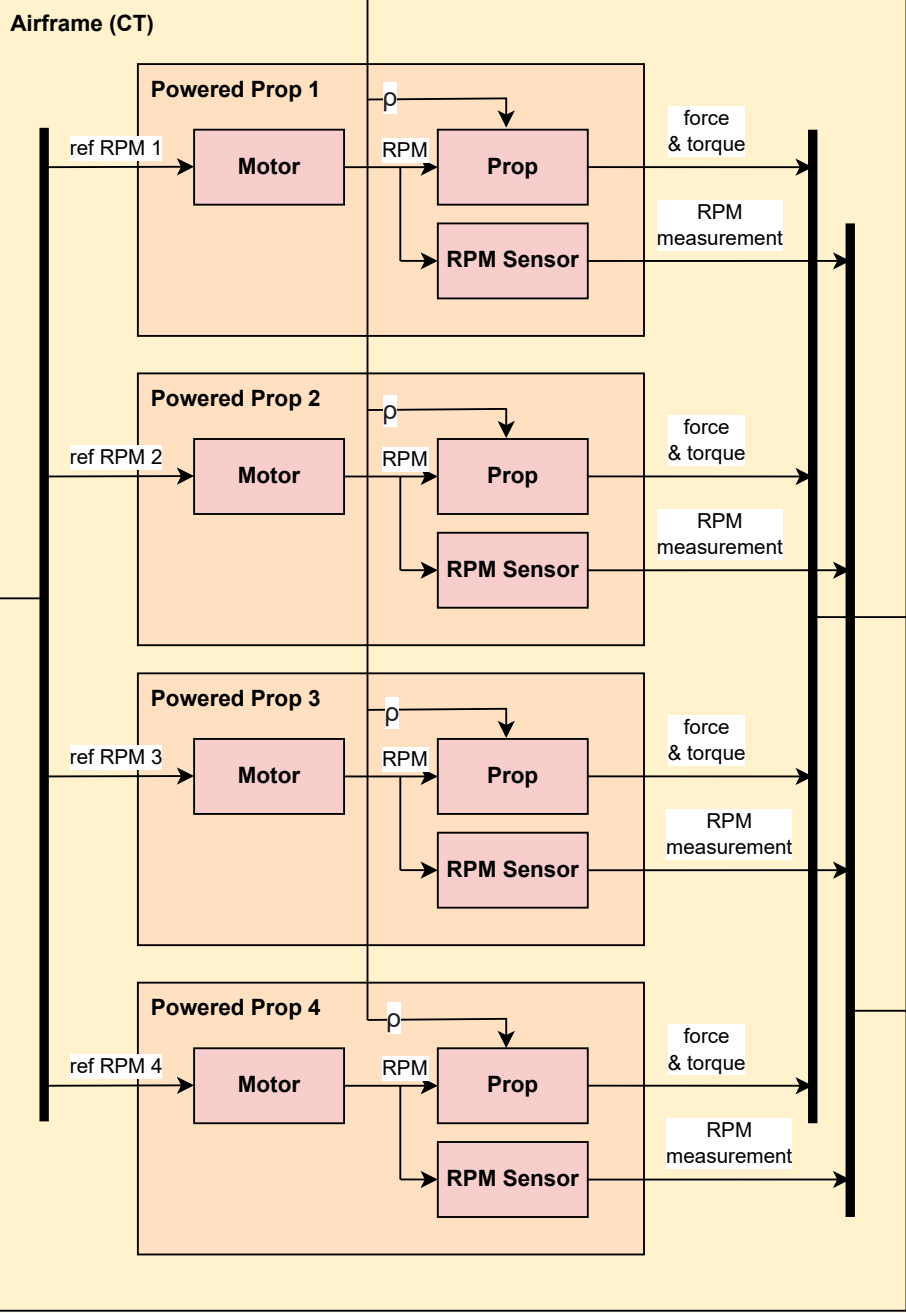
Outer Wrapper (The "WORLD")

"Task Manager"
(e.g. human with remote controls)

Atmosphere

The Drone

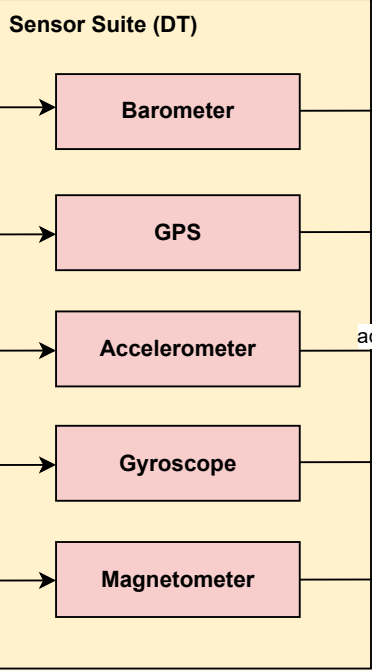
"Hardware"



"Software"

State Estimator
(e.g. Kalman Filter)

Control System
(e.g. PID, MPC...)



6DOF Rigid Body Model
(CT)