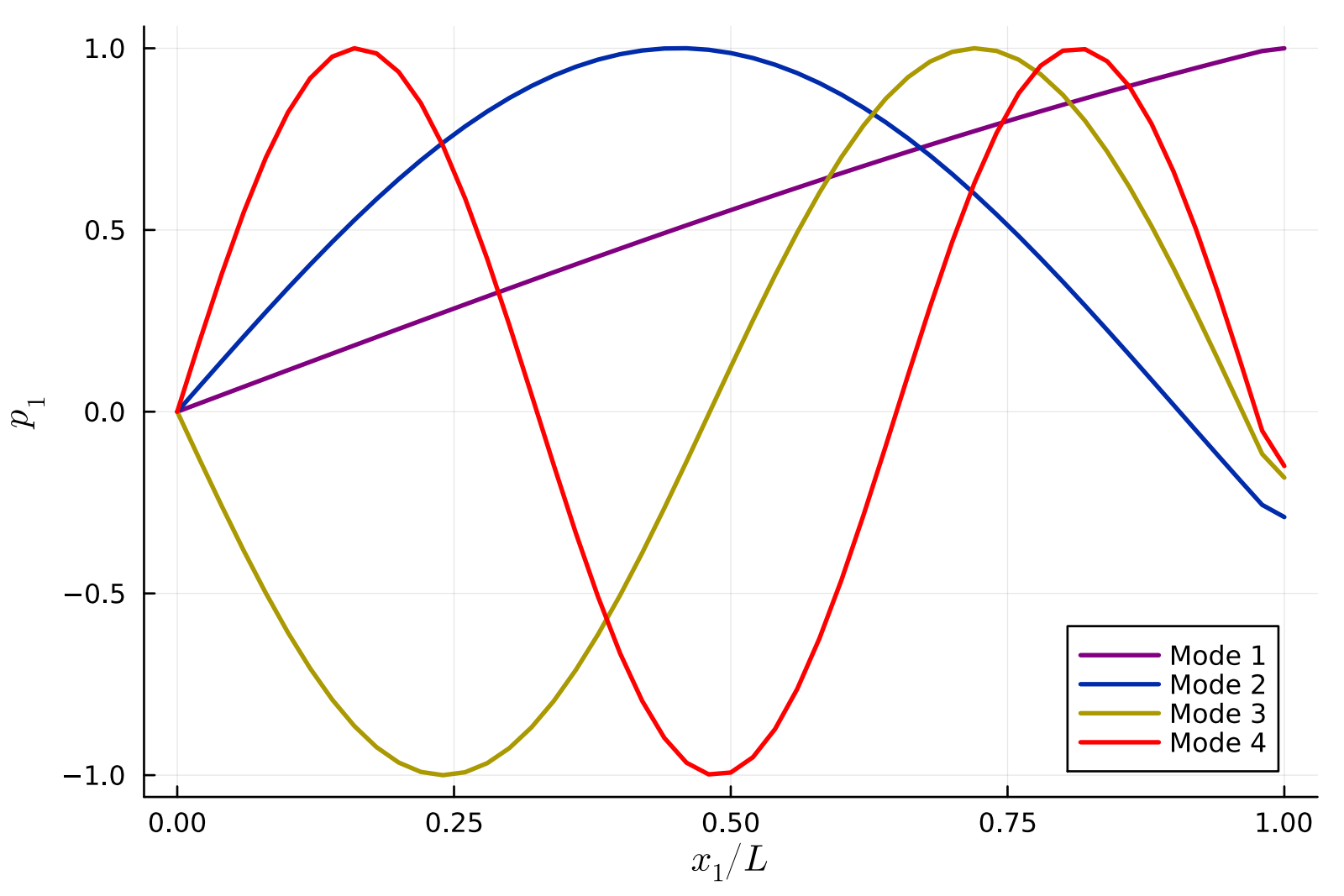

1.0
0.5
0.0
−0.5
−1.0
p_1
0.00
0.25
0.50
0.75
1.00
x_1/L
Mode 1
Mode 2
Mode 3
Mode 4