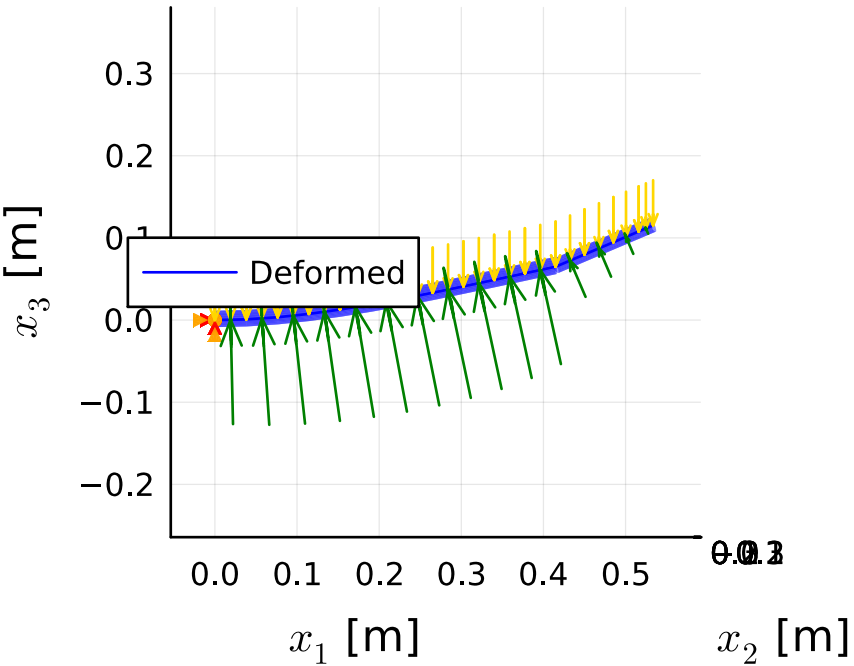

0.3
0.2
0.0
−0.1
−0.2
Deformed
x_3 [m]
0.0
0.1
0.2
0.3
0.4
0.5
x_1 [m]
x_2 [m]