
s/eLORETA

model-driven & (new) data-driven
inverse solutions for EEG/MEG

Marco Congedo,
GIPSA-lab,
CNRS, Grenoble Alpes University, Grenoble-INP

Model-Driven Linear Distributed Inverse Solutions

A short History

1984 (Hämäläinen and Ilmoniemi), 1987 (Sarvas)
Minimum Norm: no depth localization, huge localization error

1984→ (many authors)
Weighted Minimum Norm

1994 (Pascual-Marqui)
LORETA: low localization error

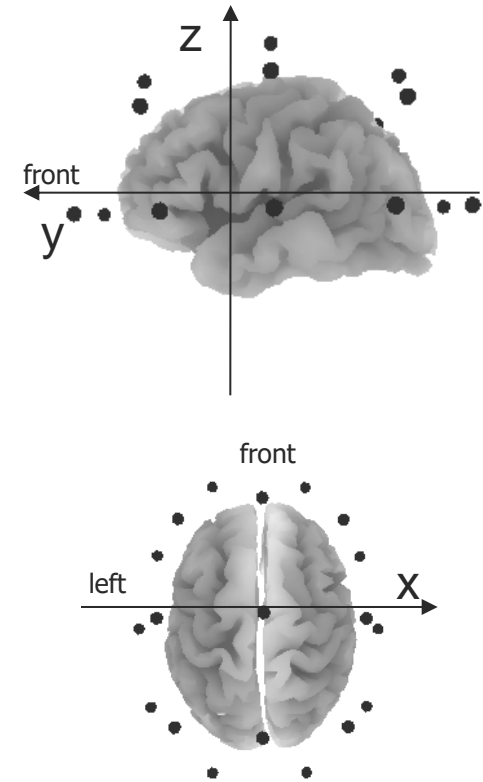
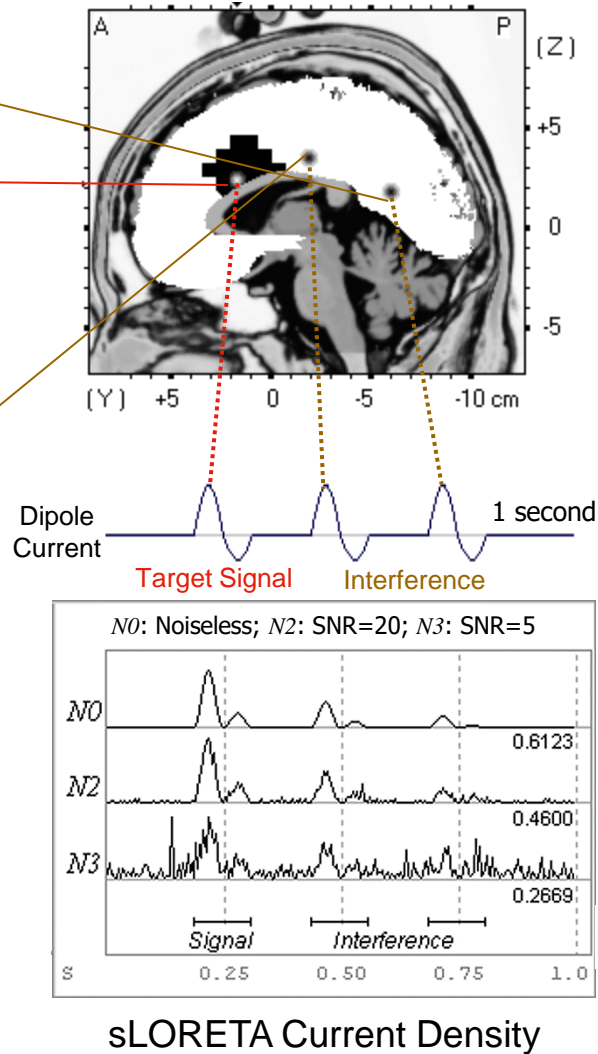
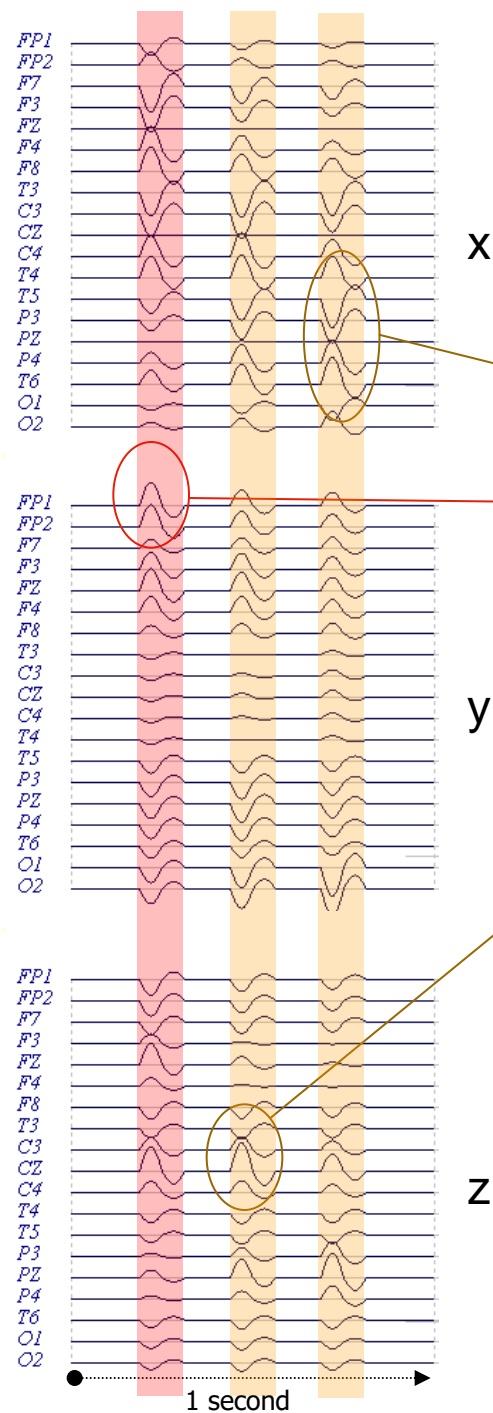
1997 (Van Veen et al.)
LCMVB: localization error, not a genuine solution

2002 (Pascual-Marqui)
sLORETA -> zero localization error, not a genuine solution

2007 (Pascual-Marqui)
eLORETA -> zero localization error and a genuine solution

All the model driven methods results in smooth, low spatial resolution reconstruction

Spatial Resolution (19 electrodes)



Notation, Nomenclature and Problem Statement

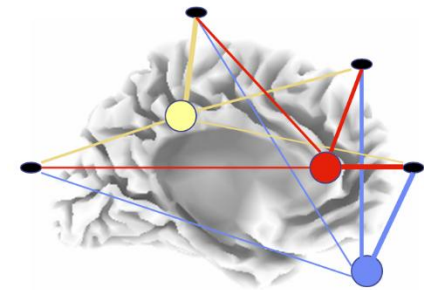
N sensors $\mathbf{x}(t) \leftarrow \mathbf{H}\mathbf{x}(t) \in \mathbb{R}^N$ is the **CAR** Sensor Measurement Vector

$\mathbf{H} = \mathbf{I} - \frac{1}{N}\mathbf{1}\mathbf{1}^T$ is the **centering matrix**

Q voxels $\mathbf{j}(t) \in \mathbb{R}^{3Q}$ Current Vector

$\mathbf{x}(t) = \mathbf{K}\mathbf{j}(t)$ *Forward problem*

$\mathbf{j}(t) = \mathbf{T}^T \mathbf{x}(t)$ *Inverse problem*



$\mathbf{K} \in \mathbb{R}^{N \cdot 3Q}$; $\mathbf{K} = [\mathbf{K}_1 \mathbf{K}_2 \dots \mathbf{K}_Q]$; $\mathbf{K}_q = [\mathbf{k}_x \mathbf{k}_y \mathbf{k}_z]_q \in \mathbb{R}^{N \cdot 3}$

Leadfield Matrix

$\mathbf{T}^T \in \mathbb{R}^{3Q \cdot N}$; $\mathbf{T} = [\mathbf{T}_1 \mathbf{T}_2 \dots \mathbf{T}_Q]$; $\mathbf{T}_q = [\mathbf{t}_x \mathbf{t}_y \mathbf{t}_z]_q \in \mathbb{R}^{N \cdot 3}$

Transfer Matrix

Notation, Nomenclature and Problem Statement

Given a leadfield matrix \mathbf{K} the inverse problem has infinite solutions \mathbf{T} .

A genuine solution should reproduce the measurement such that $\mathbf{x}(t) = \mathbf{K}\mathbf{T}^T \mathbf{x}(t) \rightarrow \mathbf{K}\mathbf{T}^T = \mathbf{H}$

and should feature zero-localization error in psf $\rightarrow \mathbf{T}^T \mathbf{K}$ is ‘block-diagonally dominant’

$$\mathbf{j}_q = \mathbf{T}_q^T \mathbf{x} \in \mathbb{R}^3$$

Single-Voxel *Current*

$$\gamma_q = \|\mathbf{j}_q\|^2 = \mathbf{x}^T \mathbf{\Xi}_q \mathbf{x}, \quad \mathbf{\Xi}_q = \mathbf{T}_q \mathbf{T}_q^T \in \mathbb{R}^{N \times N}$$

Single-Voxel *Current Density*

$$\gamma_\Omega = \sum_{q \in \Omega} \mathbf{x}^T \mathbf{\Xi}_q \mathbf{x} = \mathbf{x}^T \mathbf{\Xi}_\Omega \mathbf{x}, \quad \mathbf{\Xi}_\Omega = \sum_{q \in \Omega} \mathbf{T}_q \mathbf{T}_q^T \in \mathbb{R}^{N \times N}$$

ROI *Current Density*

Covariance (Data) and LeadField (Model)

$$\mathbf{C} = E(\mathbf{x}\mathbf{x}^T)$$

Sensor Covariance Matrix

$$\mathbf{x}(t) = \mathbf{K}\mathbf{j}(t)$$

Forward Problem

$$\mathbf{C} = \mathbf{k}_{xq}\mathbf{k}_{xq}^T$$

for 1 dipole x -oriented at voxel q and amplitude 1

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\boldsymbol{\theta}_q^T\mathbf{K}_q^T$$

for 1 dipole oriented as $\boldsymbol{\theta}_q = [x, y, z]$ at voxel q and amplitude 1

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\sigma_q^2\boldsymbol{\theta}_q^T\mathbf{K}_q^T$$

for 1 dipole oriented as $\boldsymbol{\theta}_q$ and amplitude σ_q at voxel q

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\sigma_q^2\boldsymbol{\theta}_q^T\mathbf{K}_q^T + \mathbf{K}_j\boldsymbol{\theta}_j\sigma_j^2\boldsymbol{\theta}_j^T\mathbf{K}_j^T$$

for 2 dipole oriented as $\boldsymbol{\theta}_p$ and $\boldsymbol{\theta}_q$ and amplitude σ_p and σ_q at voxel p and q

$\mathbf{K}\mathbf{K}^T$ Gram Matrix

Weighted Regularized Minimum Norm Solution

$$\mathbf{j} = \mathbf{T}^T \mathbf{x} \quad \text{Inverse problem}$$

$$\mathbf{T}^T = \mathbf{K}^T \left(\mathbf{K} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1}, \quad \alpha \geq 0 \quad \rightarrow \text{Minimum Norm}$$

$$\text{if } \alpha = 0 \text{ then } \mathbf{T}^T = \mathbf{K}^+$$

$$\mathbf{T}^T = \boldsymbol{\Theta}^{-1} \mathbf{K}^T \left(\mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1}, \quad \rightarrow \text{Weighted Minimum Norm}$$

with $\boldsymbol{\Theta} \in \mathbb{R}^{3Q \times 3Q}$ symmetric
(e.g., LORETA, eLORETA, but NOT sLORETA)

sLORETA and eLORETA

sLORETA family (NOT a genuine solution)

$$\mathbf{T}_q^T = \left[\left(\mathbf{K}_q^T \mathbf{Z} \mathbf{K}_q \right)^{-1/2} \mathbf{K}_q^T \mathbf{Z} \right]; \quad \mathbf{Z} \in \mathbb{R}^{N \cdot N} \text{ symmetric}$$

$$\mathbf{Z} = \left(\mathbf{K} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1} \rightarrow \text{sLORETA (model driven, maximum entropy, no a-priori)}$$

$$\mathbf{Z} = \left(\mathbf{C} + \alpha \mathbf{H} \right)^{-1} \rightarrow \text{sLORETA (data driven)}$$

eLORETA (a genuine solution)

$$\mathbf{T}_q^T = \boldsymbol{\Theta}_q^{-1} \mathbf{K}_q^T \left(\mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1}, \quad \boldsymbol{\Theta} \in \mathbb{R}^{3Q \cdot 3Q} \text{ symmetric and block-diagonal,}$$

$$\boldsymbol{\Theta}_q^{-1} = \left[\mathbf{K}_q^T \left(\mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1} \mathbf{K}_q \right]^{1/2}$$

$\mathbf{K} \mathbf{K}^T$ Gram Matrix

$\mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T$ Weighted Gram Matrix

eLORETA: another view

$$\Theta_q^{-1} = \left[\mathbf{K}_q^T \left(\mathbf{K} \Theta^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K}_q \right]^{\frac{1}{2}}$$

is the solution to the optimization problem:

$$\min_{\Theta} \left\| \mathbf{I} - \left[\Theta^{-1} \mathbf{K}^T \left(\mathbf{K} \Theta^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K} \Theta^{-1} \right] \right\|^2,$$

which satisfies the set of matrix equations

$$\Theta_q^2 = \mathbf{K}_q^T \left(\mathbf{K} \Theta^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K}_q, \text{ for all } q: 1 \dots Q$$

In practice: within-voxels and between-voxels uncorrelation criterium!

eLORETA algorithm

Initialize $\Theta = I \in \mathbb{R}^{3Q \cdot 3Q}$

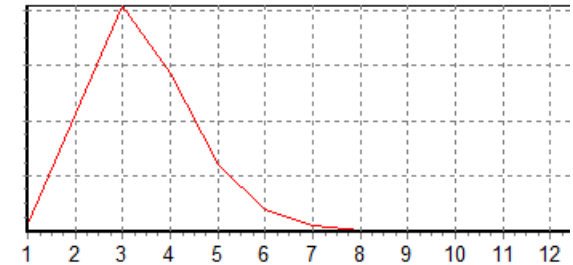
Repeat

$$\Pi = (K\Theta^{-1}K^T + \alpha H)^+ \in \mathbb{R}^{N \cdot N}$$

for each voxel q do $\Theta_q^{-1} = (K_q^T \Pi K_q)^{-\frac{1}{2}} \in \mathbb{R}^{3 \cdot 3}$

Until Convergence (small changes in Θ)

Example Convergence (N=19)



→ eLORETA (model driven)

Trick: $K\Theta^{-1}K^T = \sum_q K_q \Theta_q^{-1} K_q^T$

$$\Pi = (C + \alpha H)^+ \in \mathbb{R}^{N \cdot N}$$

for each voxel q do $\Theta_q^{-1} = (K_q^T \Pi K_q)^{-\frac{1}{2}} \in \mathbb{R}^{3 \cdot 3}$

→ eLORETA (data driven) ?

Finally compute for each voxel q $T_q^T = \Theta_q^{-1} K_q^T (K\Theta^{-1}K^T + \alpha H)^+$

Interesting Similarities

Vector Type

$$\mathbf{T}_q^T = \left[\left(\mathbf{K}_q^T \mathbf{C}^+ \mathbf{K}_q \right)^{-1/2} \mathbf{K}_q^T \mathbf{C}^+ \right] \rightarrow \text{sLORETA (data driven)}$$

$$\mathbf{T}_q^T = \left[\left(\mathbf{K}_q^T \mathbf{C}^+ \mathbf{K}_q \right)^{-1} \mathbf{K}_q^T \mathbf{C}^+ \right] \rightarrow \text{LCMV Beamforming}$$

(must be normalized somehow: Sekihara and Nagarajan, 2008)

Scalar Type

$$\mathbf{T}_q^T = \frac{\mathbf{k}_q^T \mathbf{C}^+}{\sqrt{\mathbf{k}_q^T \mathbf{C}^+ \mathbf{k}_q}} \rightarrow \text{sLORETA (data driven)}$$

$$\mathbf{T}_q^T = \frac{\mathbf{k}_q^T \mathbf{C}^+}{\mathbf{k}_q^T \mathbf{C}^+ \mathbf{k}_q} \rightarrow \text{LCMV Beamforming}$$

(must be normalized somehow)

Relevant Performance Indices

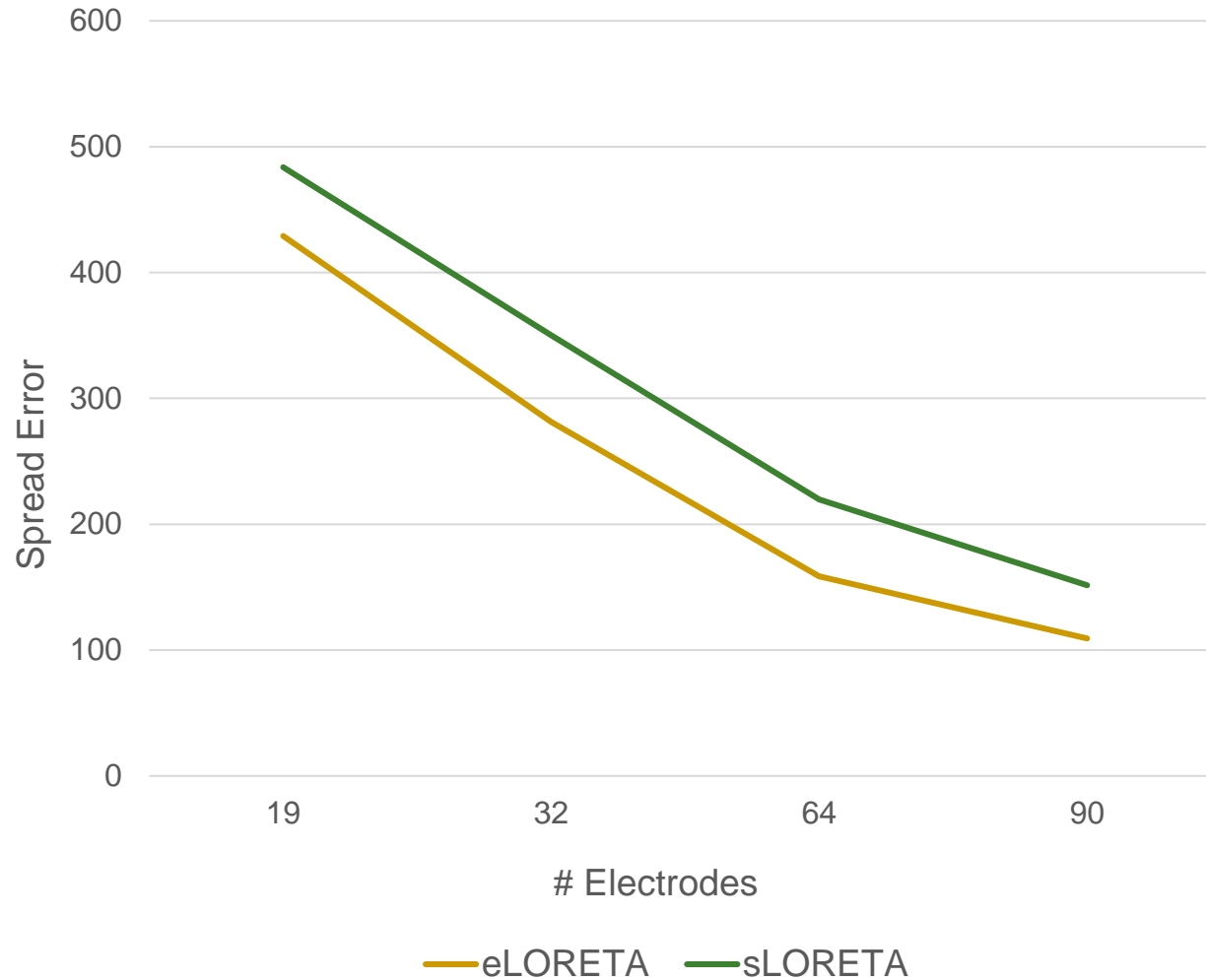
- Spread Error:

Average (energy not in test location / energy in test location)

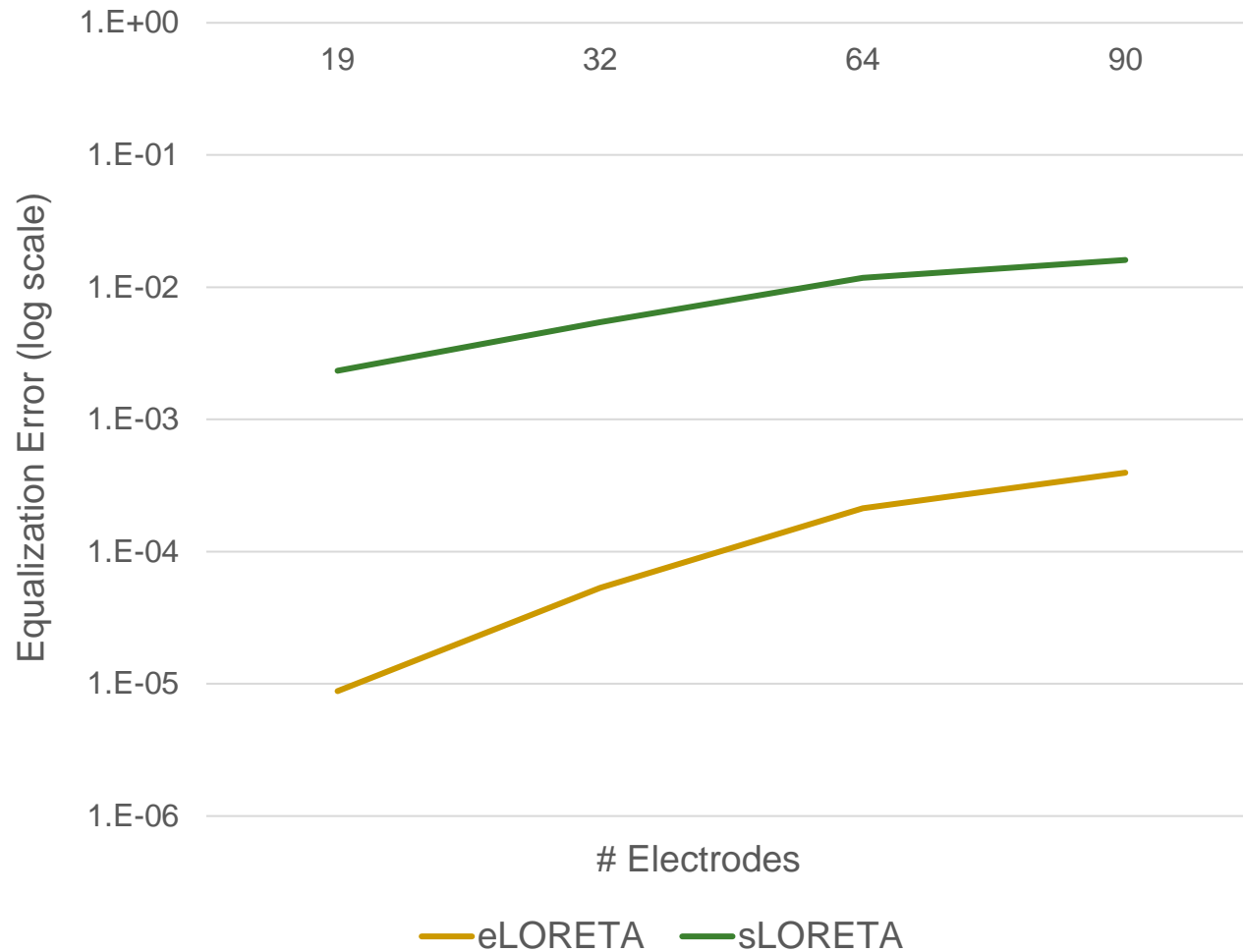
- Equalization Error:

variance of energy across test locations and orientations

Comparing sLORETA vs eLORETA



Comparing sLORETA vs eLORETA



Upper Bounds for Data Driven sLORETA

$$\mathbf{T}_q^T = \left(\mathbf{K}_q^T \mathbf{C} \mathbf{K}_q \right)^{-1/2} \mathbf{K}_q^T \mathbf{C}$$

- $\mathbf{C} = (\mathbf{K} \mathbf{K}^T)^+ \rightarrow \text{sLORETA}$
(no a-priori, maximum entropy, model-driven covariance)
- $\mathbf{C} = (\mathbf{K}_q \mathbf{K}_q^T)^+ \rightarrow \text{Position}$
- $\mathbf{C} = (\mathbf{K}_\theta \mathbf{K}_\theta^T)^+ \rightarrow \text{Orientation}$
- $\mathbf{C} = (\mathbf{k}_{q\theta} \mathbf{k}_{q\theta}^T)^+ \rightarrow \text{Position} + \text{Orientation}$

Results (1/2)

SPREAD ERROR					
electrodes	eLORETA	sLORETA	Pos+Orient	Pos	Orient
19	429.0615974	483.6912568	0.32347742	0.47575874	406.1040238
32	281.2597383	350.1400515	0.19188051	0.27920945	296.7390919
64	158.5638184	219.6632052	0.08993596	0.11086595	167.5994111
90	109.2754763	151.5266824	0.02709140	0.02887675	107.3542492

Ratio: 1495

Ratio: 5593

Results (2/2)

EQUALIZATION ERROR					
Electrodes	eLORETA	sLORETA	Pos+Orient	Pos	Orient
19	0.00000881	0.00233484	0.00002256	0.00003151	0.00794155
32	0.00005328	0.00545325	0.00001283	0.00001824	0.01568172
64	0.00021251	0.01177894	0.00000722	0.00001068	0.03443352
90	0.00039541	0.01606805	0.00000190	0.00000194	0.04777370

Ratio: 103

Ratio: 8457